IN THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application:

1.-15. (Canceled)

16. (Previously Amended) A method of infusing a fluid into a body of a user, the method comprising:

obtaining a current blood glucose concentration of the user;
generating a controller input based on the current blood glucose concentration;
generating commands by a proportional plus, integral plus, derivative (PID) controller
from the controller input using at least one preset controller gain, wherein a proportional
component and a derivative component of the PID controller may be combined to represent a
first phase insulin response, and an integral component of the PID controller represents a second
phase insulin response; and

infusing the fluid based on the commands from the PID controller; wherein the PID controller accurately estimates a hypoglycemic glucose excursion.

17. - 31. (Canceled)

32. (Previously Amended) A system for infusing a fluid into a body of a user, the system comprising:

means for obtaining a current blood glucose concentration of the user;
means for generating a controller input based on the current blood glucose concentration;
means for generating commands by a proportional plus, integral plus, derivative (PID)
controller from the controller input using at least one preset controller gain, wherein a
proportional component and a derivative component of the PID controller may be combined to
represent a first phase insulin response, and an integral component of the PID controller
represents a second phase insulin response; and

means for infusing the fluid based on the commands from the PID controller; wherein the PID controller accurately estimates a hypoglycemic glucose excursion.

33. - 34. (Canceled)

- 35. (Previously Presented) The method of infusing a fluid into a body of a user in accordance with claim 16, wherein the PID controller is a bilinear PID controller.
- 36. (Previously Presented) The system for infusing a fluid into a body of a user in accordance with claim 32, wherein the PID controller is a bilinear PID controller.